

CIMR-F7Z

Varispeed F7

The industrial workhorse

- Flux vector control with or without PG
- Silent operation. No current de-rating in silent mode.
- Torque control
- PID control
- Powerful application oriented functionality
- Stand still autotuning
- High slip braking
- Energy saving function.
- Standard LCD operator
- Standard RS485 communications - Modbus
- Fieldbus options: DeviceNet, PROFIBUS, CANOpen
- Embedded OMRON PLC functionality with PLC option card.
- PC configuration tool: CX-Drive.
- CE, UL, and cUL marking

Customized software *

- The inverter software can be customized to meet specific application. Examples:
- Electronic line shaft (S-8169)
- Crane software (S-7071)

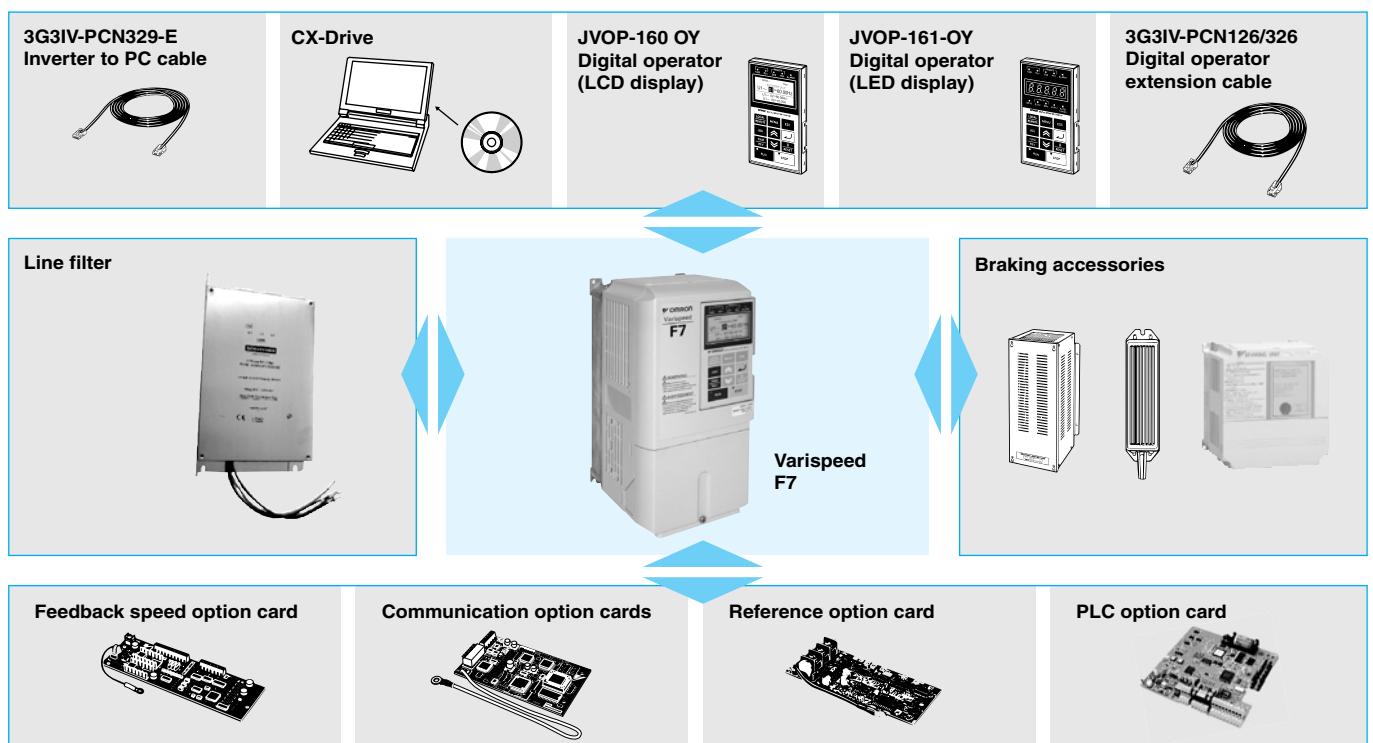
* For detailed information please see CASE software section.

Ratings

- 200 V Class three-phase 0.4 to 110 kW
- 400 V Class three-phase 0.4 to 300 kW

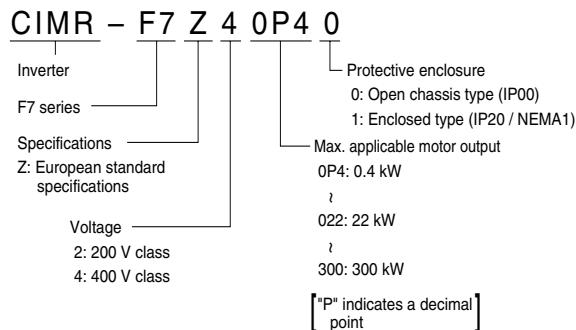


System configuration



Specifications

Type designation



200 V class

Model CIMR-F7Zo		20P4	20P7	21P5	22P2	23P7	25P5	27P5	2011	2015	2018	2022	2030	2037	2045	2055	2075	2090	2110		
Max. applicable motor output¹		0.55	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	75	90	110		
Output characteristics		Inverter capacity	kVA	1.2	1.6	2.7	3.7	5.7	8.8	12	17	22	27	32	44	55	69	82	110	130	160
Rated current		A		3.2	4.1	7.0	9.6	15	23	31	45	58	71	85	115	145	180	215	283	346	415 ²
Max. voltage		3-phase, 200/208/220/230/240 V (proportional to input voltage)																			
Max. output frequency		Heavy duty (low carrier, constant torque applications): 150 Hz max Normal duty 1 or 2 (high/reduced carrier, variable torque applications): 400 Hz max																			
Power supply		Rated input voltage and frequency																			
		3-phase 200/208/220/230/240 V, 50/60 Hz ³																			
		Allowable voltage fluctuation																			
		+10%, -15%																			
		Allowable frequency fluctuation																			
Harmonic wave prevention		DC reactor	Option										Provided								
		12-pulse input	Not available										Available ⁴								

- Our standard 4-pole motors are used for max. applicable motor output. Choose the inverter model whose rated current is allowable within the motor rated current range.
- 322 A in case of heavy duty mode
- When using the inverter of 200 V class 37 kW or more with a cooling fan of three-phase 230 V 50 Hz or 240 V 50/60 Hz power supply, a transformer for the cooling fan is required.
- A 3-wired transformer is required at 12-pulse input.

400 V class

Model CIMR-F7Zo		40P4	40P7	41P5	42P2	43P7	44P0	45P5	47P5	4011	4015	4018	4022	4030	4037	4045	4055	4075	4090	4110	4132	4160	4185	4220	4300		
Max. applicable motor output¹		0.55	0.75	1.5	2.2	3.7	4.0	5.5	7.5	11	15	18.5	22	30	37	45	55	75	90	110	132	160	185	220	300		
Output characteristics		Inverter capacity	kVA	1.4	1.6	2.8	4.0	5.8	6.6	9.5	13	18	24	30	34	46	57	69	85	110	140	160	200	230	280	390	510
		Rated current	A	1.8	2.1	3.7	5.3	7.6	8.7	12.5	17	24	31	39	45	60	75	91	112	150	180	216	260	304	370	506 ²	675 ³
		Max. voltage																									
		3-phase, 380/400/415/440/460/480 V (proportional to input voltage)																									
		Max. output frequency																									
Power supply		Rated input voltage and frequency																									
		3-phase 380/400/415/440/460/480 V, 50/60 Hz																									
		Allowable voltage fluctuation																									
		+10%, -15%																									
		Allowable frequency fluctuation																									
Harmonic wave prevention		DC reactor	Option										Provided														
		12-Pulse input	Not available										Available ⁴														

- Our standard 4-pole motors are used for max. applicable motor output. Choose the inverter model whose rated current is allowable within the motor rated current range.
- 405 A in case of heavy duty mode
- 540 A in case of heavy duty mode
- A 3-wired transformer is required at 12-pulse input.

Common specifications

Enclosures

	Model CIMR-F7Z□	20P4	20P7	21P5	22P2	23P7	25P5	27P5	2011	2015	2018	2022	2030	2037	2045	2055	2075	2090	2110					
200 V class	Enclosed type - IP20)	Available as standard					Available for option					N/A												
	Open chassis type - IP00	Available by removing the upper and lower cover of enclosed type					Available as standard																	
400 V class	Model CIMR-F7Z□	40P4	40P7	41P5	42P2	43P7	45P5	47P5	4011	4015	4018	4022	4030	4037	4045	4055	4075	4090	4110	4132	4160	4185	4220	4300
	Enclosed type - IP20	Available as standard					Available for option					N/A												
	Open chassis type - IP00	Available by removing the upper and lower cover of enclosed type					Available as standard																	

Common specifications

Model number CIMR-F7Z□	Specification
Control characteristics	Control method Sine wave PWM Closed loop vector control, open loop vector control, V/f control, V/f with PG control
	Torque characteristics Heavy duty (low carrier, constant torque applications): 2 kHz carrier frequency, 150% overload for 1 minute, higher carrier frequency possible with current derating. Normal duty 1 (high carrier, variable torque applications): maximum carrier frequency, depending on inverter capacity, 120% overload for 1 minute. Normal duty 2 (variable torque applications): carrier frequency reduced, continuous overload capability increased
	Speed control range 1:40 (V/f control) 1:100 (open loop vector control) 1:1000 (closed loop vector control)
	Speed control accuracy ± 3% (V/f control) ± 0.03% (V/f control with PG) ± 0.2% (open loop vector control) ± 0.02% (closed loop vector control) (25 °C ± 10 °C)
	Speed control response 5 Hz (control without PG) 30 Hz (control with PG)
	Torque limits Provided (4 quadrant steps can be changed by constant settings.) (Vector control)
	Torque accuracy ± 5%
	Frequency range 0.01 to 150 Hz (Heavy Duty), 0.01 to 400 Hz (Normal Duty 1 or 2)
	Frequency accuracy (temperature characteristics) Digital references: ± 0.01% (-10 °C to +40 °C) Analog references: ± 0.1% (25°C ±10°C)
	Frequency setting resolution Digital references: 0.01 Hz Analog references: 0.025/50 Hz (11 bits plus sign)
	Output frequency resolution 0.01 Hz
	Overload capacity and maximum current Heavy duty (low carrier, constant torque applications): 150% of rated output current for 1 minute Normal duty 1 or 2 (high/reduced carrier, variable torque applications): 120% of rated output current for 1 minute
	Frequency setting signal 0 to +10V, -10 to +10 V, 4 to 20 mA, pulse train
	Accel/decel time 0.01 to 6000.0 s (4 selectable combinations of independent acceleration and deceleration time settings)
	Braking torque Approximately 20% (approximately 125% with braking resistor option, braking transistor built into inverters of 18.5 kW or less)
	Main control functions Restarting after momentary power loss, speed search, overtorque/undertorque detection, torque limits, 17-speed control (maximum), 4 acceleration and deceleration times, S-curve acceleration/deceleration, 3-wire control, auto-tuning (rotational or stationary), dwell function, cooling fan ON/OFF control, slip compensation, torque compensation, auto-restart after fault, jump frequencies, upper and lower limits for frequency references, DC braking for starting and stopping, high-slip braking, advanced PID control, energy-saving control, MEMOBUS communications (RS-485/422, 19.2 kbps maximum), 2 motor parameter sets, fault reset and parameter copy function.
Protective functions	Motor protection Protection by electronic thermal overload relay.
	Instantaneous overcurrent protection Stops at approx. 200% of rated output current.
	Fuse blown protection Stops for fuse blown.
	Overload protection Heavy duty (low carrier, constant torque applications): 150% of rated output current for 1 minute Normal duty 1 (high carrier, variable torque applications): 120% of rated output current for 1 minute Normal duty 2 (high carrier, variable torque applications): 120% of rated output current for 1 minute, increased continuous output current.
	Oversupply protection 200 class inverter: stops when main-circuit DC voltage is above 410 V. 400 class inverter: stops when main-circuit DC voltage is above 820 V.
	Undervoltage protection 200 class inverter: stops when main-circuit DC voltage is below 190 V. 400 class inverter: stops when main-circuit DC voltage is below 380 V.
	Momentary power loss ride through By selecting the momentary power loss method, operation can be continued if power is restored within 2 s.
	Cooling fin overheating Protection by thermistor.
	Stall prevention Stall prevention during acceleration, deceleration and running independently.
	Grounding protection Protection by electronic circuits.
Environment	Charge indicator Illuminates when the main circuit DC voltage is approx. 10 VDC or more.
	Ambient operating temperature -10 °C to 40 °C (enclosed wall-mounted type) -10 °C to 45 °C (open chassis type)
	Ambient operating humidity 95% max. (with no condensation)
	Storage temperature -20 °C to + 60 °C (short-term temperature during transportation)
	Application site Indoor (no corrosive gas, dust, etc.)
	Altitude 1000 m max.
	Vibration 10 to 20 Hz, 9.8 m/s ² max.; 20 to 50 Hz, 2 m/s ² max



Dimensions

Open chassis type (IEC IP00)

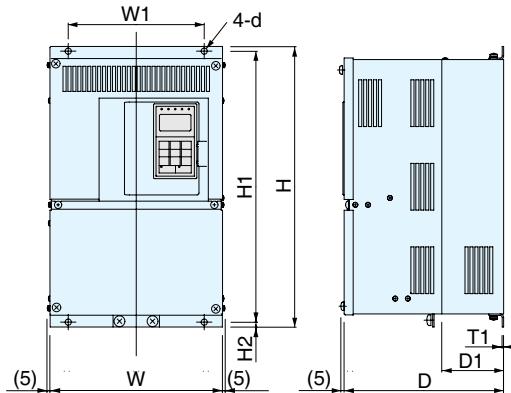


Fig 1

Voltage	Max. applicable motor output kW	Inverter CIMR-F7Z□	Fig	Dimensions in mm									Approx. weight kg	Cooling method	
				W	H	D	W1	H1	H2	D1	T1	d			
200 V class (3-phase)	0.4	-----	1	250	400	258	195	385	7.5	100	2.3	M6	21	Fan cooled	
	0.75	-----										24			
	1.5	-----										57			
	2.2	-----										63			
	3.7	-----										86			
	5.5	-----										87			
	7.5	-----										108			
	11	-----										150			
	15	-----													
	18.5	-----													
	22	2022 0		275	400	258	195	385	7.5	100	2.3	M6	21		
	30	2030 0			450	220	435	12.5	100	130	3.2	M10	24		
	37	2037 0			600	298	250						57		
	45	2045 0			328	328	575						63		
	55	2055 0			450	348	325						86		
	75	2075 0			725	500	850	700					87		
	90	2090 0			358	370	820	15	100	140	4.5	M12	108		
	110	2110 0			378	445	855						150		
400 V class (3-phase)	0.4	-----													
	0.75	-----													
	1.5	-----													
	2.2	-----													
	4.0	-----													
	5.5	-----													
	7.5	-----													
	11	-----													
	15	-----													
	18.5	-----													
	22	4022 0		275	450	258	220	435	7.5	100	2.3	M6	21	Fan cooled	
	30	4030 0			550	283	260	535					36		
	37	4037 0			325	325	348	700					88		
	45	4045 0			550	260	325	820	12.5	105	3.2	M10	89		
	55	4055 0			348	450	725	12.5					102		
	75	4075 0			378	500	850	140					120		
	90	4090 0			445	575	916	1440	15	1270	4.5	M12	160		
	110	4110 0			445	710	1305	125.5					260		
	132	4132 0			540	710	1475	1440					280		
	160	4160 0			540	710	1475	1440					405		
	185	4185 0			540	710	1475	1440							
	220	4220 0			540	710	1475	1440							
	300	4300 0			540	710	1475	1440							

Enclosed type (IEC IP20)

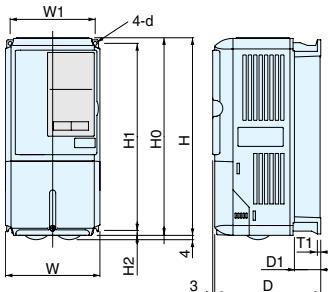
F7Z 20P41 to F7Z25P51
F7Z40P41 to F7Z45P51


Fig 1

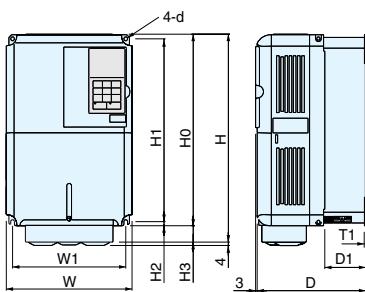
F7Z 27P51 to F7Z20181
F7Z47P51 to F7Z40181


Fig 2

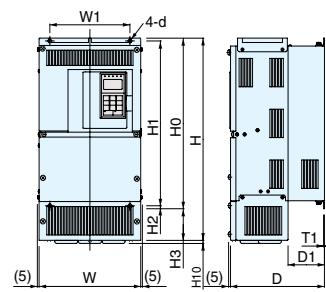
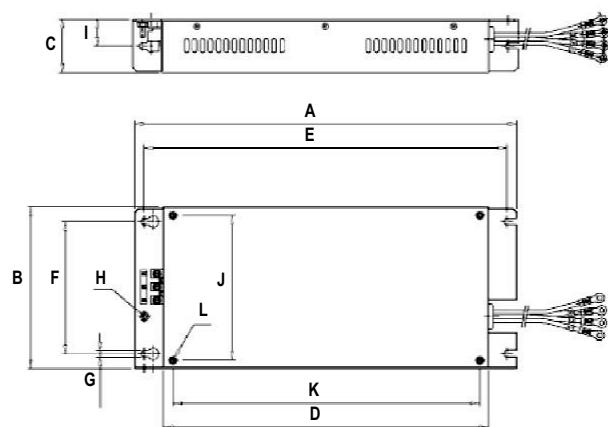
F7Z 20221 to F7Z20751
F7Z40221 to F7Z41601


Fig 3

Voltage	Max. applicable motor output kW	Inverter CIMR-F7Z□	Fig	Dimensions in mm												Approx. weight kg	Cooling method											
				W	H	D	W1	H0	H1	H2	H3	D1	T1	d														
200 V class (3-phase)	0.4	20P4 1	1	140	280	157	126	280	266	7	---	39	5	M5	3	Self cooled												
	0.75	20P7 1																										
	1.5	21P5 1																										
	2.2	22P2 1				177																						
	3.7	23P7 1																										
	5.5	25P5 1																										
	7.5	27P5 1	2	200	300	197	186	300	285	8	0	65.5	2.3	M6	6	Fan cooled												
	11	2011 1																										
	15	2015 1		240	350	207	216	350	335	7.5	0	78																
	18.5	2018 1																										
	22	2022 1	3	254	535	258	195	400	385	8	0	65.5	12.5	M10	11	Fan cooled												
	30	2030 1																										
	37	2037 1		279	615	209	220	450	435																			
	45	2045 1																										
	55	2055 1		380	809	250	600	575	700																			
	75	2075 1																										
400 V class (3-phase)	0.4	40P4 1	1	140	280	157	126	280	266	7	---	39	5	M5	3	Self Cooled												
	0.75	40P7 1																										
	1.5	41P5 1																										
	2.2	42P2 1		200	300	197	186	300	285	8	0	65.5	2.3	M6	6	Fan cooled												
	3.7	43P7 1																										
	4.0	44P0 1		240	350	207	216	350	335																			
	5.5	45P5 1																										
	7.5	47P5 1	2	200	300	197	186	300	285	8	---	65.5	105	M10	40	Fan cooled												
	11	4011 1																										
	15	4015 1		240	350	207	216	350	335																			
	18.5	4018 1																										
	22	4022 1	3	275	535	258	220	450	435	7.5	85	100	130	M12	130	4.5	Fan cooled											
	30	4030 1																										
	37	4037 1		325	715	283	260	550	535																			
	45	4045 1																										
	55	4055 1		453	1027	348	325	725	700	12.5	302	130																
	75	4075 1																										
	90	4090 1		504	1243	358	370	850	820	15	393																	
	110	4110 1																										
	132	4132 1		579	1324	378	445	918	855	45.8	408	140																
	160	4160 1																										

Filters

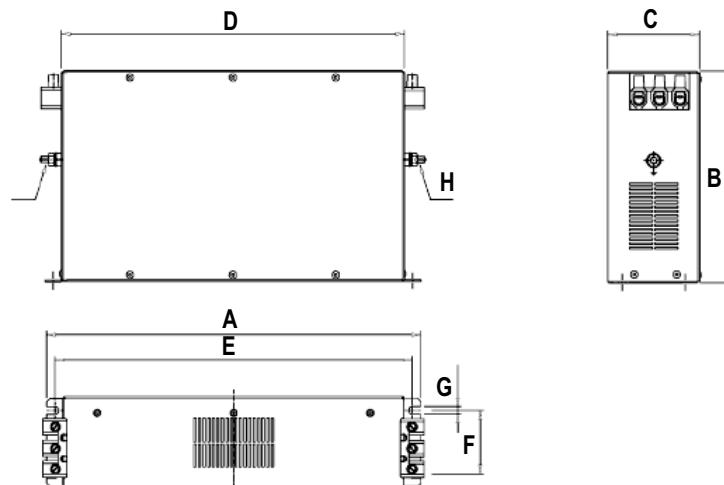
Footprint / Flat filters



Model	Dimensions												
	A	B	C	D	E	F	G	H	I	J	K	L	
200 V	3G3RV-PFI2035-SE	330	141	46	281	313	115	5.5	M5	23	126	266	M5
	3G3RV-PFI2060-SE	355	206	60	302	336	175	6.5	M6	30	186	285	M6
	3G3RV-PFI2100-SE	408	236	80	355	390	205	6.5	M6	40	216	335	M6
400 V	3G3RV-PFI3010-SE	330	141	46	281	313	115	5.5	M5	23	126	266	M5
	3G3RV-PFI3018-SE	330	141	46	281	313	115	5.5	M5	23	126	266	M5
	3G3RV-PFI3021-SE	355	206	50	302	336	175	6.5	M4	25	186	285	M5
	3G3RV-PFI3035-SE	355	206	50	302	336	175	6.5	M5	25	186	285	M6
	3G3RV-PFI3060-SE	408	236	65	355	390	205	6.5	M6	32.5	216	335	M6
	3G3RV-PFI3410-SE ¹	386	115	260	306	240	235	12.0	M12	-	-	-	-
	3G3RV-PFI3600-SE ¹	386	135	260	306	240	235	12.0	M12	-	-	-	-
	3G3RV-PFI3800-SE ¹	564	160	300	516	420	275	9.0	M12	-	-	-	-

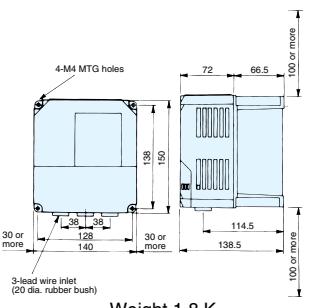
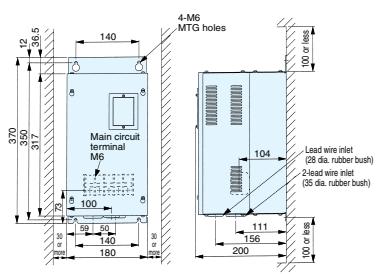
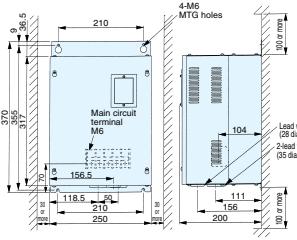
1. Flat filters are not possible to be mounted as footprint filters.

Bookform filters



Model	Dimensions								
	A	B	C	D	E	F	G	H	
200 V	3G3RV-PFI2130-SE	366	180	90	280	310	65	6.5	M10
	3G3RV-PFI2160-SE	451	170	120	350	380	102	6.5	M10
	3G3RV-PFI2200-SE	610	240	130	480	518	90	8.2	M10
400 V	3G3RV-PFI3070-SE	331	185	80	300	329	55	6.5	M6
	3G3RV-PFI3100-SE	326	150	90	240	270	65	6.5	M10
	3G3RV-PFI3130-SE	370	180	90	280	310	65	6.5	M10
	3G3RV-PFI3170-SE	451	170	120	350	380	102	6.5	M10
	3G3RV-PFI3200-SE	610	240	130	480	518	90	8.3	M10

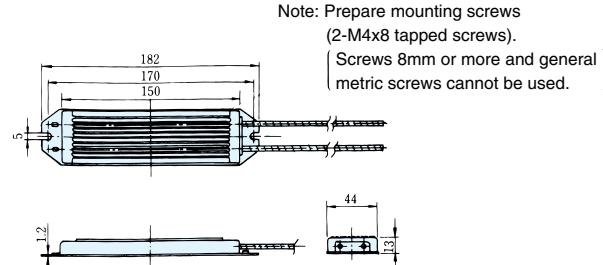
Braking unit

Model CDBR-2015 B, -2022 B, -4030B, -4045 B	Model CDBR-2110 B
 Weight 1.8 K	 Weight 8.5 Kg
Model CDBR-4220 B	
 Weight 12 Kg	

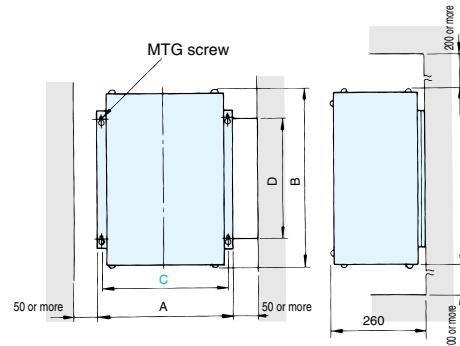
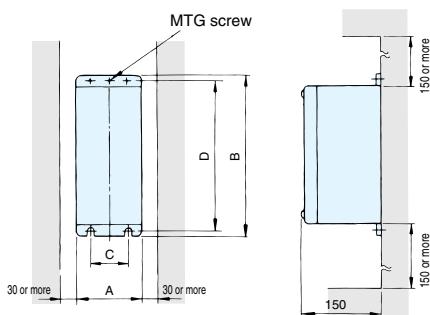
Braking resistor unit (inverter-mounted type)



Weight: 0.2 kg
Model ERF-150WJ



Braking resistor unit (separately-installed type)



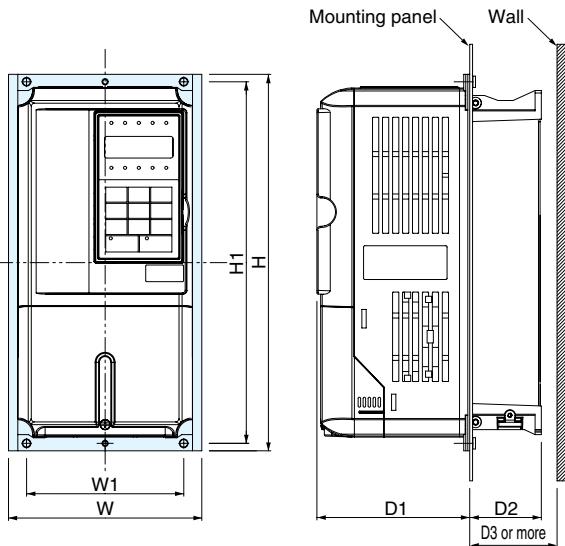
Voltage	Model LKEB-	Dimensions in mm					Weight kg
		A	B	C	D	MTG screw	
220 V class	20P7	105	275	50	260	M5 x 3	3.0
	21P5	130	350	75	335	M5 x 4	4.5
	22P2	130	350	75	335	M5 x 4	4.5
	23P7	130	350	75	335	M5 x 4	5.0
	25P5	250	350	200	335	M6 x 4	7.5
	25P5	250	350	200	335	M6 x 4	8.5
400 V class	40P7	105	275	50	260	M5 x 3	3.0
	41P5	130	350	75	335	M5 x 4	4.5
	42P2	130	350	75	335	M5 x 4	4.5
	43P7	130	350	75	335	M5 x 4	5.0
	45P5	250	350	200	332	M6 x 4	7.5
	47P5	250	350	200	332	M6 x 4	8.5

Voltage	Model LKEB-	Dimensions in mm					Weight kg
		A	B	C	D	MTG screw	
220 V class	2011	266	543	246	340	M8 x 4	10
	2015	356	543	336	340	M8 x 4	15
	2018	446	543	426	340	M8 x 4	19
	2022	446	543	426	340	M8 x 4	19
400 V class	4011	350	412	330	325	M6 x 4	16
	4015	350	412	330	325	M6 x 4	18
	4018	446	543	426	340	M8 x 4	19
	4022	446	543	426	340	M8 x 4	19
	4030	356	956	336	740	M8 x 4	25
	4037	446	956	426	740	M8 x 4	33
	4045	446	956	426	740	M8 x 4	33

Attachments

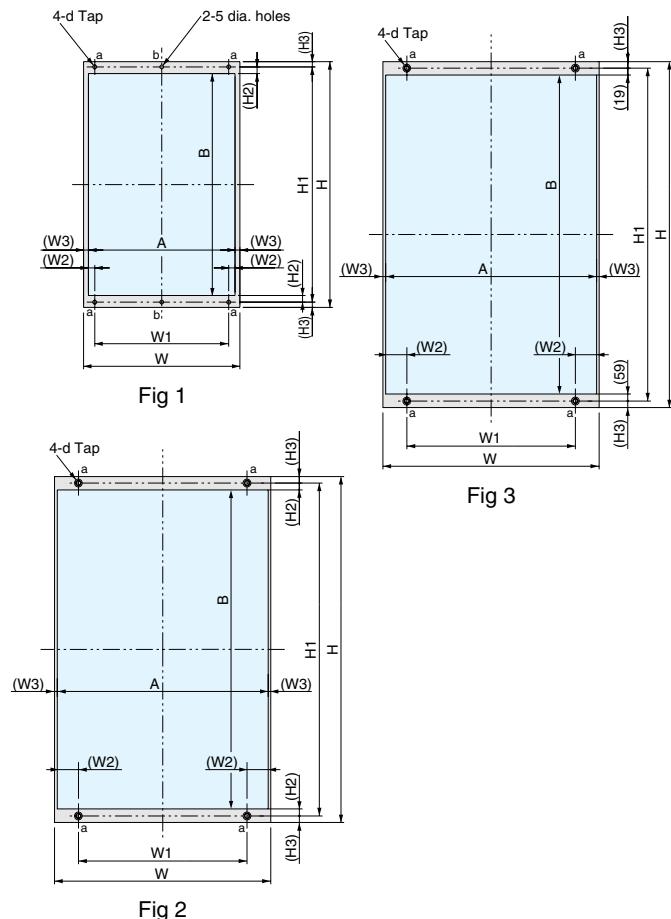
Heatsink external mounting attachment

The Varispeed G7 inverters under the 200/400 V class 15 kW or less need this attachment for mounting the heatsink externally. This attachment expands the outer dimensions of the width and height of the inverter. (Attachment is not required for inverters of 18.5 kW or more.)



CIMR-G7C□	Attachment order code	Dimensions in mm						
		W	H	W1	H1	D1	D2	D3
20P4	EZZ08676A	155	302	126	290	122.6	37.4	40
20P7								
21P5								
22P2								
23P7	EZZ08676B	210	330	180	316	136.1	63.4	70
25P5								
27P5								
2011								
2015	EZZ08676C	250	392	216	372	133.6	76.4	85
40P4								
40P7								
41P5								
42P2	EZZ08676A	155	302	126	290	122.6	37.4	40
43P7								
45P5								
47P5								
4011	EZZ08676C	250	392	216	372	133.6	76.4	85
4015								

Panel cut for external mounting of cooling fin (heatsink)

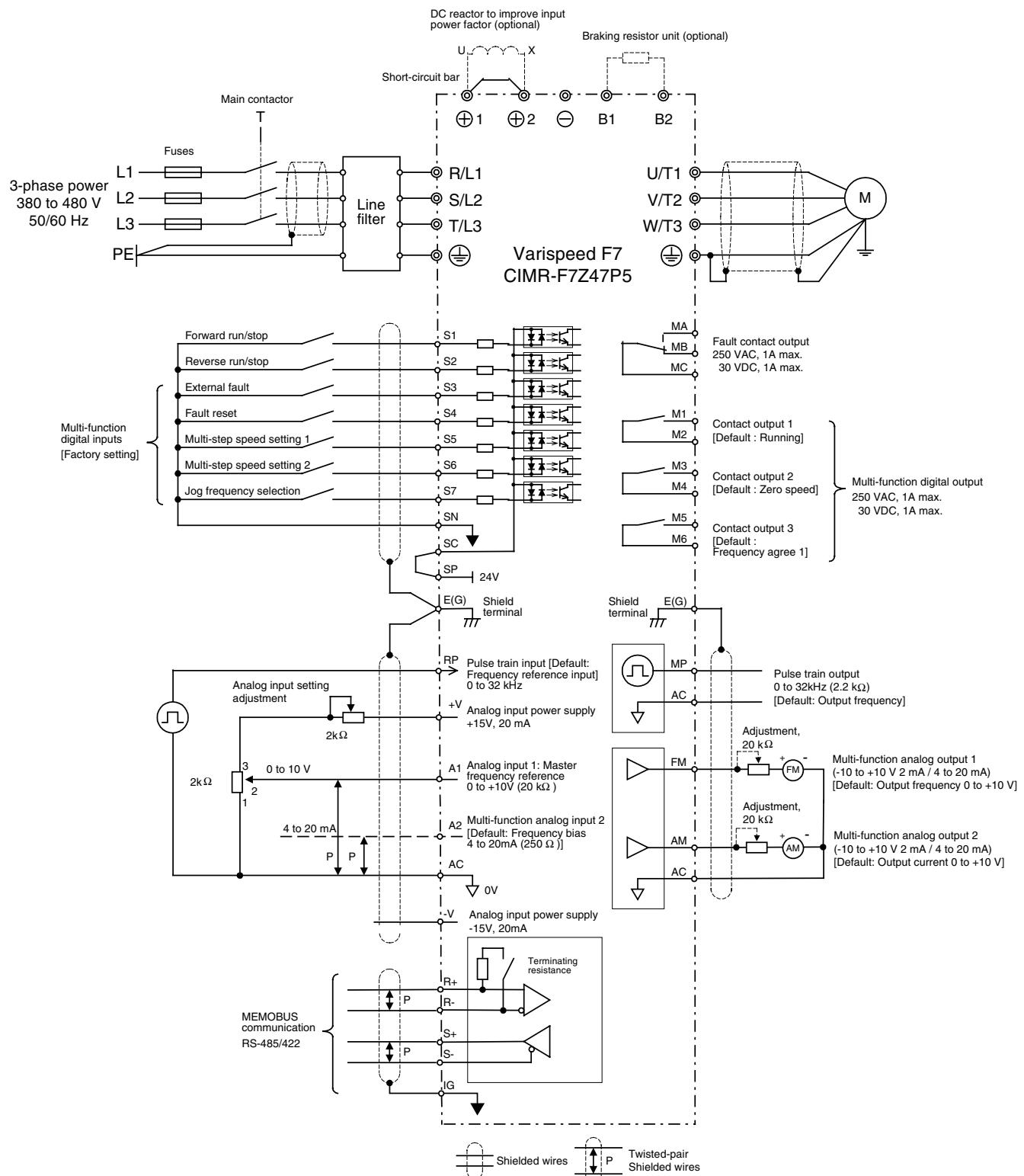


CIMR-F7Z□	Fig	Dimensions in mm									
		W	H	W1	(W2)	(W3)	H1	(H2)	(H3)	A	B
20P4	1	155	302	126	6	8.5	290	9.5	6	138	271
20P7											
21P5											
22P2											
23P7	2	210	330	180	8.5	316	9	7	197	298	M5
25P5											
27P5											
2011											
2015	1	250	392	216	8.5	372	9.5	10	233	353	M6
2018											
2022											
2030											
2037	2	375	600	250	54.5	8	575	15	12.5	359	545
2045											
2055											
2075											
2090	1	500	850	370	57	8	820	19	15	484	782
2110											
40P4											
40P7											
41P5	1	155	302	126	6	8.5	290	9.5	6	138	271
42P2											
43P7											
44P0											
45P5	2	210	330	180	8.5	316	9	7	197	298	M5
47P5											
4011											
4015											
4018	1	250	392	216	8.5	372	9.5	10	233	353	M6
4022											
4030											
4037											
4045	2	325	550	260	24.5	8	535	7.5	309	519	M10
4055											
4075											
4090											
4110	1	500	850	370	57	8	820	19	15	484	782
4132											
4160											
575											

1. The sizes are different between the top and the bottom. Refer Fig 3

Installation

Standard connections



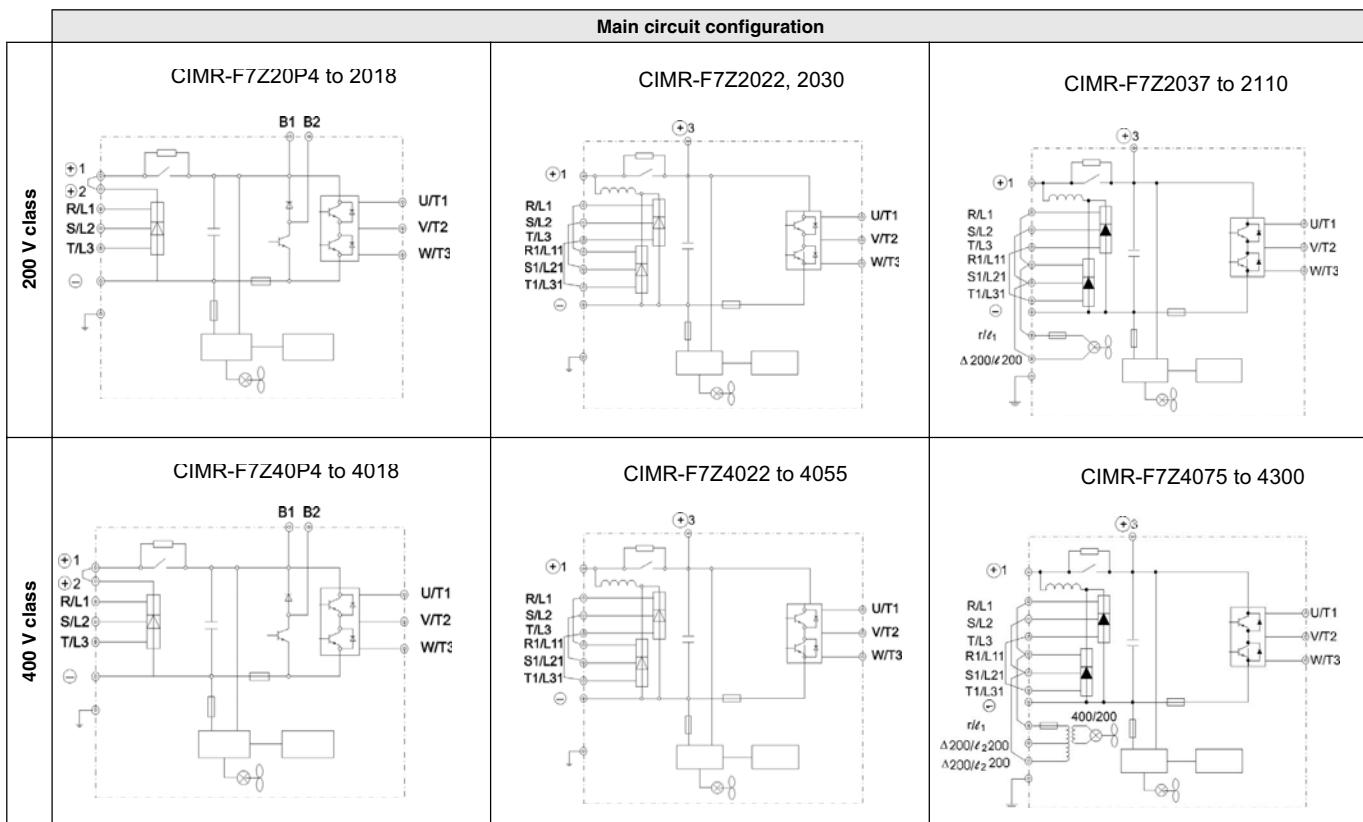
Main circuit

Voltage	200 V			400 V		
Model CIMR-F7Z□	20P4 to 2018	2022, 2030	2037 to 2110	40P4 to 4018	4022 to 4055	4075 to 4300
Max. applicable motor output	0.4 to 18.5 kW	22 to 30 kW	37 to 110 kW	0.4 to 18.5 kW	22 to 55 kW	75 to 300 kW
R/L1	Main circuit input power supply	Main circuit input power supply R-R1, S-S1 and T-T1 have been wired before shipment (See P59).	Main circuit input power supply R-R1, S-S1 and T-T1 have been wired before shipment	Inverter output		
S/L2						
T/L3						
R1/L11						
S1/L21						
T1/L31						
U/T1	Braking resistor unit	Braking resistor unit	Braking resistor unit	Inverter output		
V/T2				Inverter output		
W/T3				Inverter output		
B1				Inverter output		
B2	•DC reactor (⊕1- ⊖2) •DC power supply ¹ (⊕1 - ⊖)	•DC power supply (⊕1- ⊖2) •Braking unit (⊕3 - ⊖)	•DC reactor (⊕1- ⊖2) •DC power supply ¹ (⊕1 - ⊖)	Braking resistor unit		
⊖				Braking resistor unit		
⊕1				Braking resistor unit		
⊕2				Braking resistor unit		
⊕3	---	Cooling fan power supply ²	---	Braking resistor unit		
↙I ₂				Braking resistor unit		
r/I ₁				Braking resistor unit		
↙200 / I ₂ 200				Braking resistor unit		
↙400 / I ₂ 400	Ground terminal (100 Ω or less)	Ground terminal (100 Ω or less)	Ground terminal (100 Ω or less)	Ground terminal (100 Ω or less)		
⊕				Ground terminal (100 Ω or less)		

1. ⊕1 - ⊖ DC power input does not conform to UL/c-UL listed standard.

2. Cooling fan power supply r/I₁ - ↙I₂: 200 to 220 VAC 50 Hz, 200 to 230 VAC 60 Hz
(A transformer is required for 230 V 50 Hz or 240 V 50/60 Hz power supply.)

3. Cooling fan power supply r/I₁ - ↙ 200 / I₂ 200: 200 to 220 VAC 50 Hz, 200 to 230 VAC 60 Hz, r/I₁ - ↙ 400 / I₂ 400: 380 to 480 VAC 50/60 Hz

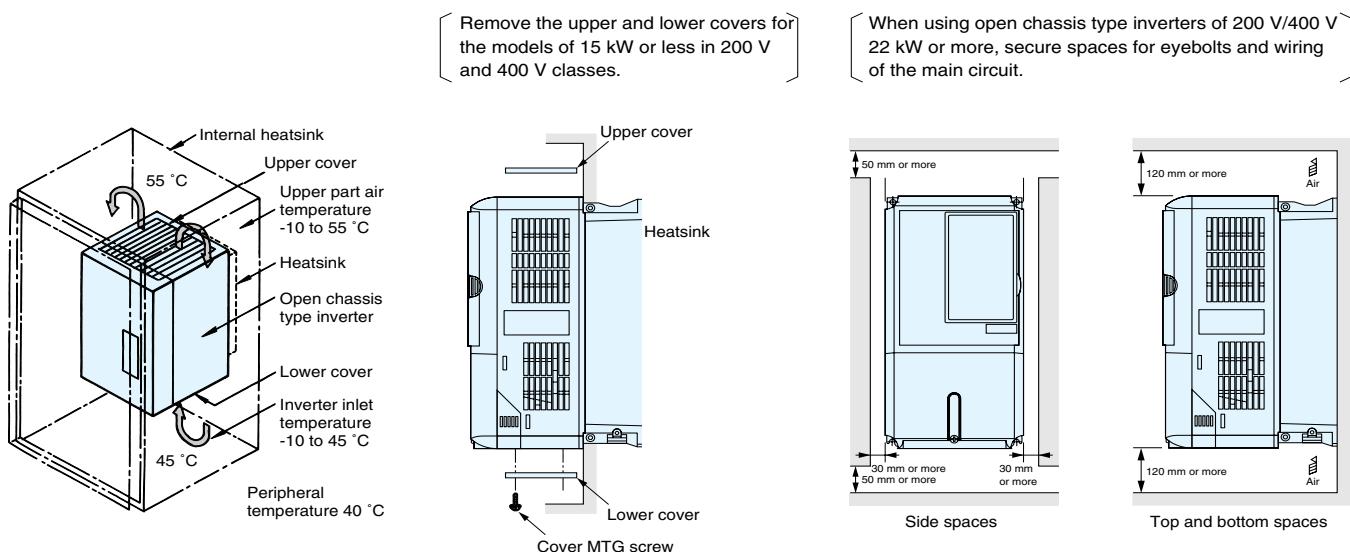


Control circuit

Type	No.	Signal name	Function	Signal level
Digital input signals	S1	Forward run/stop command	Forward run when ON; stopped when OFF.	24 VDC, 8 mA photocoupler
	S2	Reverse run/stop command	Reverse run when ON; stopped when OFF.	
	S3	External fault input ¹	Fault when ON.	
	S4	Fault reset ¹	Reset when ON	
	S5	Multi-step speed reference 1 ¹ (master/auxiliary switch)	Auxiliary frequency reference when ON.	
	S6	Multi-step speed reference 2 ¹	Multi-step setting 2 when ON.	
	S7	Jog frequency reference ¹	Jog frequency when ON.	
	SC	Digital input common	—	
Analog input signals	SN	Digital input neutral	—	—
	SP	Digital input power supply	+24 VDC power supply for digital inputs	24 VDC, 250 mA max. ²
	+V	15 V power output	15 V power supply for analog references	15 V (max. current: 20 mA)
	-V	-15 V power output	-15 V power supply for analog references	-15 V (max. current: 20 mA)
	A1	Frequency reference	-10 to +10 V/100%	-10 to +10 V(20 kΩ)
	A2	Multi-function analog input	4 to 20 mA/100% -10 V to +10 V/100%	Function is selected by setting H3-09. 4 to 20 mA(250 Ω) -10 V to +10 V(20 kΩ)
	AC	Analog reference common	—	—
Sequence output signals	E(G)	Shield wire, optional ground line connection point	—	—
	M1	Running signal (1NO contact)	Operating when ON.	Multi-function contact outputs Relay contacts Contact capacity: 1 A max. at 250 VAC 1 A max. at 30 VDC ³
	M2	—	—	
	M3	Zero speed	Zero level (b2-01) or below when ON	
	M4	—	—	
	M5	Speed agreement detection	Within ±2 Hz of set frequency when ON.	Relay contacts Contact capacity: 1 A max. at 250 VAC 1 A max. at 30 VDC ³
	M6	—	—	
	MA	Fault output signal	Fault when CLOSED across MA and MC Fault when OPEN across MB and MC	
	MB	—	—	
	MC	—	—	
Analog output signals	FM	Multi-function analog output (frequency output)	0 to 10 V, 10V=100% output frequency	Multi-function analog output 1 -10 to +10 V max. ±5% 2 mA max.
	AC	Analog common	—	4 to 20 mA current output
	AM	Multi-function analog output (current monitor)	0 to 10 V, 10V=200% inverter's rated current	
Pulse I/O	RP	Pulse input ⁴	H6-01 (frequency reference input)	0 to 32 kHz (3 kΩ) High level voltage 3.5 to 13.2 V
	MP	Pulse monitor	H6-06 (output frequency)	0 to 32 kHz +15 V output (2.2 kΩ)
RS-485/422	R+	MEMOBUS communications input	For 2-wire RS-485, short R+ and S+ as well as R- and S-.	Differential input, photocoupler isolation
	R-	—		—
	S+	MEMOBUS communications output		Differential input, photocoupler isolation
	S-	—	—	—
	IG	Signal common	—	—

- The default settings are given for terminals S3 to S7. For a 3-wire sequence, the default settings are a 3-wire sequence for S5, multi-step speed setting 1 for S6 and multi-step speed setting 2 for S7.
- Do not use this power supply for supplying any external equipment.
- When driving a reactive load, such as a relay coil with DC power supply, always insert a flywheel diode.
- Pulse input specifications are given in the following table.

Low level voltage	0.0 to 0.8 V
High level voltage	3.5 to 13.2 V
H duty	30% to 70%



Inverter heat loss

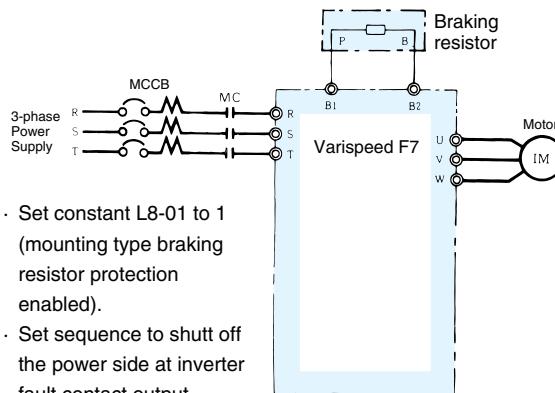
200 V class

Model CIMR-F7Z□		20P4	20P7	21P5	22P2	23P7	25P5	27P5	2011	2015	2018	2022	2030	2037	2045	2055	2075	2090	2110	
Inverter capacity		kVA	1.2	1.6	2.7	3.7	5.7	8.8	12	17	22	27	32	44	55	69	82	110	130	160
Rated current		A	3.2	4.1	7.0	9.6	15	23	31	45	58	71	85	115	145	180	215	283	346	415
Heat loss W	Fin	W	20	27	50	70	112	164	219	374	429	501	586	865	1015	1266	1588	2019	2437	2733
Heat loss W	Inside unit	W	39	42	50	59	74	84	113	170	183	211	274	352	411	505	619	838	997	1242
Heat loss W	Total heat loss	W	59	69	100	129	186	248	332	544	612	712	860	1217	1426	1771	2207	2857	3434	3975
Fin coding		Self cooled				Fan cooled														

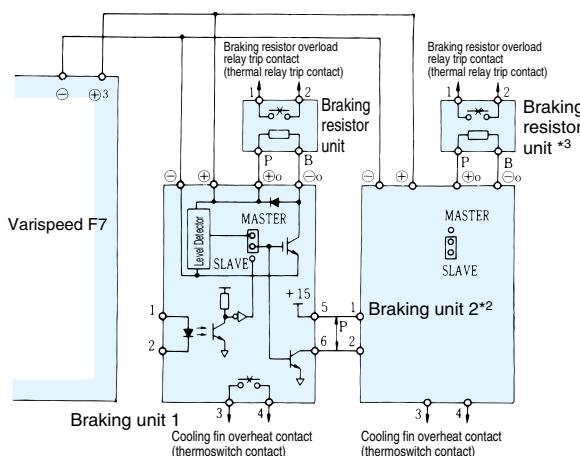
400 V class

Model CIMR-F7Z□		40P4	40P7	41P5	42P2	43P7	44P0	45P5	47P5	4011	4015	4018	4022	4030	4037	4045	4055	4075	4090	4110	4132	4160	4185	4220	4300	
Inverter capacity		kVA	1.4	1.6	2.8	4.0	5.8	6.0	9.5	13	18	24	30	34	46	57	69	85	110	140	160	200	230	280	390	510
Rated current		A	1.8	2.1	3.7	5.3	7.6	8.0	12.5	17	24	31	39	45	60	75	91	112	150	180	216	260	304	370	506	675
Heat loss W	Fin	W	14	17	36	59	80	91	127	193	252	326	426	466	678	784	901	1203	1399	1614	2097	2388	2791	3237	3740	5838
Heat loss W	Inside unit	W	39	41	48	56	68	70	82	114	158	172	208	259	317	360	415	495	575	671	853	1002	1147	1372	1537	2320
Heat loss W	Total heat loss	W	53	58	84	115	148	161	209	307	410	498	634	725	995	1144	1316	1698	1974	2285	2950	3390	3938	4609	5277	8158
Fin coding		Self cooled				Fan cooled																				

Connections for braking units

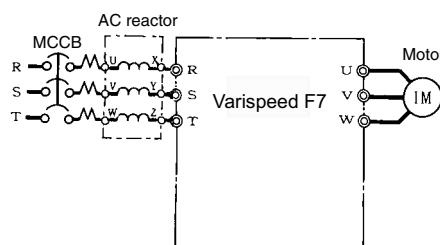


Connections for braking resistors

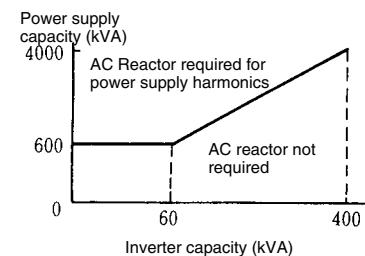


AC reactor

Connection example

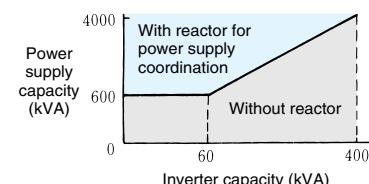
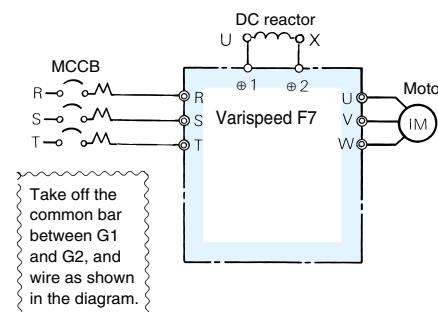


Application example



200 V class			400 V class		
Max. applicable motor output kW	Current value A	Inductance mH	Max. applicable motor output kW	Current value A	Inductance mH
0.4	2.5	4.2	0.4	1.3	18.0
0.75	5	2.1	0.75	2.5	8.4
1.5	10	1.1	1.5	5	4.2
2.2	15	0.71	2.2	7.5	3.6
3.7	20	0.53	3.7	10	2.2
5.5	30	0.35	5.5	15	1.42
7.5	40	0.265	7.5	20	1.06
11	60	0.18	11	30	0.7
15	80	0.13	15	40	0.53
18.5	90	0.12	18.5	50	0.42
22	120	0.09	22	60	0.36
30	160	0.07	30	80	0.26
37	200	0.05	37	90	0.24
45	240	0.044	45	120	0.18
55	280	0.038	55	150	0.15
75	360	0.026	75	200	0.11
90	500	0.02	90/110	250	0.09
110	500	0.02	132/160	330	0.06
			185	490	0.04
			220		
			300	660	0.03

DC reactor



200 V class			400 V class		
Max. applicable motor output kW	Current value A	Inductance mH	Max. applicable motor output kW	Current value A	Inductance mH
0.4	5.4	8	0.4	3.2	28
0.75			0.75		
1.5	18	3	1.5	5.7	11
2.2			2.2		
3.7			3.7		
5.5	36	1	5.5	23	3.6
7.5			7.5		
11	72	0.5	11	33	1.9
15			15		
18.5	90	0.4	18.5	47	1.3
22 to 110	Built-in		22 to 300	Built-in	

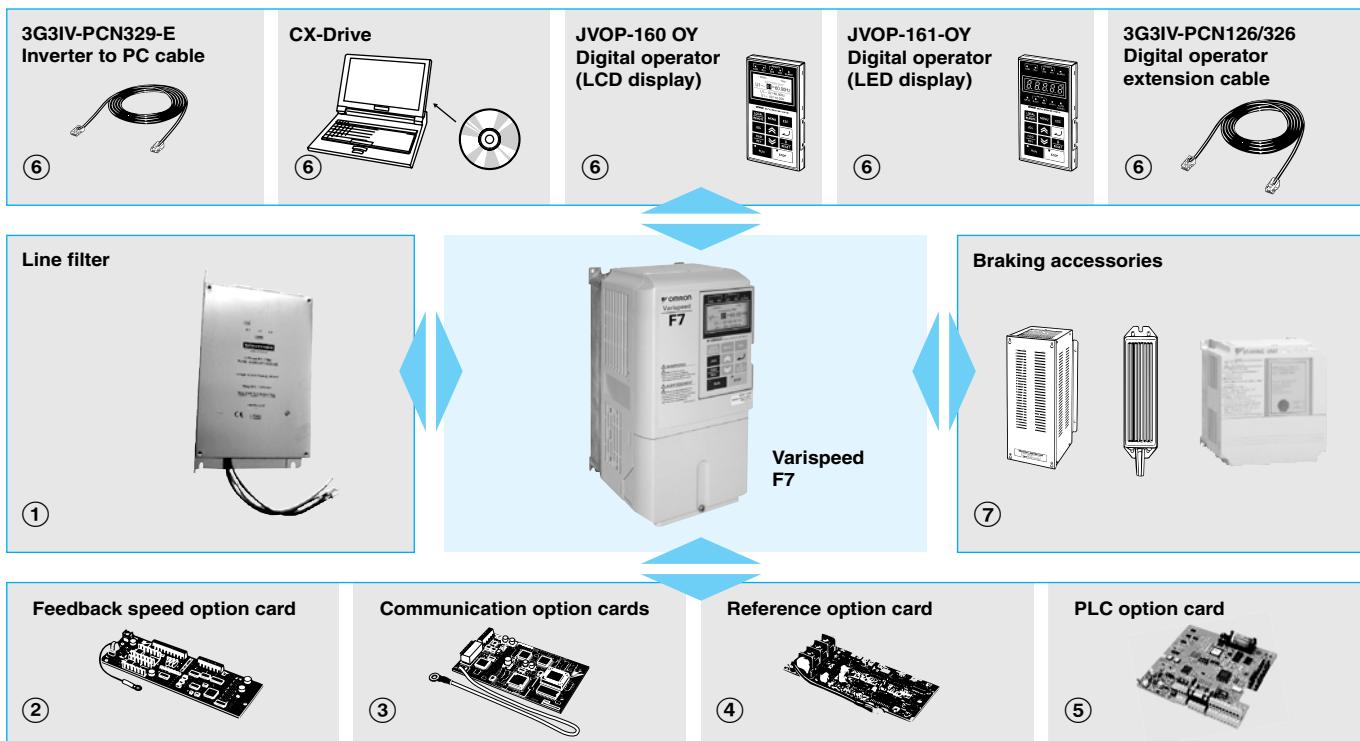
Fuse installation

To protect the inverter, it is recommended to use semiconductor fuses as shown in the table below

Inverter type	FUSE		
	Voltage (V)	Current (A)	I ² t (A ² s)
20P4	240	10	12~25
20P7	240	10	12~25
21P5	240	15	23~55
22P2	240	20	34~98
23P7	240	30	82~220
25P5	240	40	220~610
27P5	240	60	290~1300
2011	240	80	450~5000
2015	240	100	1200~7200
2018	240	130	1800~7200
2022	240	150	870~16200
2030	240	180	1500~23000
2037	240	240	2100~19000
2045	240	300	2700~55000
2055	240	350	4000~55000
2075	240	450	7100~64000
2090	240	550	11000~64000
2110	240	600	13000~83000

Inverter type	FUSE		
	Voltage (V)	Current (A)	I ² t (A ² s)
40P4	480	5	6~55
40P7	480	5	6~55
41P5	480	10	10~55
42P2	480	10	18~55
43P7	480	15	34~72
44P0	480	20	50~570
45P5	480	25	100~570
47P5	480	30	100~640
4011	480	50	150~1300
4015	480	60	400~1800
4018	480	70	700~4100
4022	480	80	240~5800
4030	480	100	500~5800
4037	480	125	750~5800
4045	480	150	920~13000
4055	480	150	1500~13000
4075	480	250	3000~55000
4090	480	300	3800~55000
4110	480	350	5400~23000
4132	480	400	7900~64000
4160	480	450	14000~250000
4185	480	600	20000~250000
4220	480	700	34000~400000
4300	480	900	52000~920000

Ordering information



Varispeed F7



200 V

Specifications		Model
IP20	0.55 Kw	3.2 A
	0.75 Kw	4.1 A
	1.5 Kw	7.0 A
	2.2 Kw	9.6 A
	3.7 Kw	15 A
	5.5 Kw	23 A
	7.5 Kw	31 A
	11 Kw	45 A
	15 Kw	58 A
	18.5 Kw	71 A
IP00	22 Kw	85 A
	30 Kw	115 A
	37 Kw	145 A
	45 Kw	180 A
	55 Kw	215 A
	75 Kw	283 A
	90 Kw	346 A
	110 Kw	415 A

400 V

Specifications		Model
IP20	0.55 Kw	1.8 A
	0.75 Kw	2.1 A
	1.5 Kw	3.7 A
	2.2 Kw	5.3 A
	3.7 Kw	7.6 A
	4.0 Kw	8.7 A
	5.5 Kw	12.5 A
	7.5 Kw	17 A
	11 Kw	24 A
	15 Kw	31 A
IP00	18.5 Kw	39 A
	22 Kw	45 A
	30 Kw	60 A
	37 Kw	75 A
	45 Kw	91 A
	55 Kw	112 A
	75 Kw	150 A
	90 Kw	180 A
	110 Kw	216 A
	132 Kw	260 A
	160 Kw	304 A
	185 Kw	370 A
	220 Kw	506 A
	300 Kw	675 A
	CIMR-F7Z43000	

① Line filters



200 V

Inverter model	Line filters				
Varispeed F7	Type	EN55011 class	Current (A)	Weight (kg)	
CIMR-F7Z20P4	3G3RV-PFI3010-SE	B, 25 m A, 100 m	10	1.2	
CIMR-F7Z20P7					
CIMR-F7Z21P5					
CIMR-F7Z22P2	3G3RV-PFI3018-SE	B, 25 m A, 100 m	18	1.3	
CIMR-F7Z23P7	3G3RV-PFI2035-SE	B, 25 m A, 100 m	35	1.4	
CIMR-F7Z25P5					
CIMR-F7Z27P5	3G3RV-PFI2060-SE	B, 25 m A, 100 m	60	3	
CIMR-F7Z2011					
CIMR-F7Z2015	3G3RV-PFI2100-SE	B, 25 m A, 100 m	100	4.9	
CIMR-F7Z2018					
CIMR-F7Z2022	3G3RV-PFI2130-SE	A, 100 m	130	4.3	
CIMR-F7Z2030					
CIMR-F7Z2037	3G3RV-PFI2160-SE	A, 100 m	160	6.0	
CIMR-F7Z2045	3G3RV-PFI2200-SE	A, 100 m	200	11.0	
CIMR-F7Z2055					
CIMR-F7Z2075	3G3RV-PFI3400-SE	A, 100 m	400	8.6	
CIMR-F7Z2090					
CIMR-F7Z2110	3G3RV-PFI3600-SE	A, 100 m	600	11.0	

400 V

Inverter model	Line filter				
Varispeed F7	Model	EN 55011 class*	Current (A)	Weight (kg)	
CIMR-F7Z40P4					
CIMR-F7Z40P7	3G3RV-PFI3010-SE	B, 25 m A, 100 m	10	1.2	
CIMR-F7Z41P5					
CIMR-F7Z42P2					
CIMR-F7Z43P7					
CIMR-F7Z44P0	3G3RV-PFI3018-SE	B, 25 m A, 100 m	18	1.3	
CIMR-F7Z45P5					
CIMR-F7Z47P5	3G3RV-PFI3021-SE	B, 25 m A, 100 m	21	1.8	
CIMR-F7Z4011	3G3RV-PFI3035-SE	B, 25 m A, 100 m	35	2.2	
CIMR-F7Z4015	3G3RV-PFI3060-SE	B, 25 m A, 100 m	60	4.0	
CIMR-F7Z4018					
CIMR-F7Z4022	3G3RV-PFI3070-SE	B, 25 m A, 100 m	70	3.4	
CIMR-F7Z4030					
CIMR-F7Z4037	3G3RV-PFI3100-SE	A, 100 m	100	4.5	
CIMR-F7Z4045					
CIMR-F7Z4055	3G3RV-PFI3130-SE	A, 100 m	130	4.7	
CIMR-F7Z4075	3G3RV-PFI3170-SE	A, 100 m	170	6.0	
CIMR-F7Z4090	3G3RV-PFI3200-SE	A, 100 m	250	11	
CIMR-F7Z4110					
CIMR-F7Z4132	3G3RV-PFI3400-SE	A, 100 m	400	8.5	
CIMR-F7Z4160					
CIMR-F7Z4185	3G3RV-PFI3600-SE	A, 100 m	600	11.0	
CIMR-F7Z4220					
CIMR-F7Z4300	3G3RV-PFI3800-SE	A, 100 m	800	31.0	

② Feedback speed control cards

Type	Model	Description	Function
Feedback speed control card	PG-A2 / 3G3FV-PPGA2	PG speed controller card (used for V/f control with PG or flux vector)	<ul style="list-style-type: none"> Phase A pulse (single pulse) inputs (voltage, complementary, open collector input) PG frequency range: Approx. 30 kHz max. [Power supply output for PG: +12 V, max. current 200 mA] Pulse monitor output: +12 V, 20 mA
	PG-B2 / 3G3FV-PPGB2		<ul style="list-style-type: none"> Phase A and B pulse inputs (exclusively for complementary input) PG frequency range: Approx. 30 kHz max. [Power supply output for PG: +12 V, max. current 200 mA] Pulse monitor output: Open collector, +24 V, Max. current 30 mA
	PG-D2 / 3G3FV-PPGD2		<ul style="list-style-type: none"> Phase A pulse (differential pulse) input for V/f control (RS-422 input) PG frequency range: Approx. 300 kHz max. [Power supply output for PG: +5 V or +12 V, max. current 200 mA] Pulse monitor output: RS-422
	PG-X2 / 3G3FV-PPGX2		<ul style="list-style-type: none"> Phase A, B and Z pulse (differential pulse) inputs (RS-422 input) PG frequency range: Approx. 300 kHz max. [Power supply output for PG: +5 V or +12 V, max. current 200 mA] Pulse monitor output: RS-422
	PG-Z2		<ul style="list-style-type: none"> Phase A, B and Z pulse (differential pulse) inputs (RS-422 input) PG frequency range: Approx. 300 kHz max. [Power supply output for PG: +5 V or +12 V, max. current 200 mA] Pulse monitor output: RS-422 Dual channel encoder: 1st channel A, B, Z / 2nd channel A, B, Z or open collector.

③ Communication option cards

Type	Model	Description	Function
Communication option card	3G3RV-PDRT2	DeviceNet option card	<ul style="list-style-type: none"> Used for running or stopping the inverter, setting or referencing parameters, and monitoring output frequency, output current, or similar items through DeviceNet communication with the host controller.
	SI-P1	PROFIBUS-DP option card	<ul style="list-style-type: none"> Used for running or stopping the inverter, setting or referencing parameters, and monitoring output frequency, output current, or similar items through PROFIBUS-DP communication with the host controller.
	SI-S1	CANopen option card	<ul style="list-style-type: none"> Used for running or stopping the inverter, setting or referencing parameters, and monitoring output frequency, output current, or similar items through CANopen communication with the host controller.
	SI-J	LONWORKS option card	<ul style="list-style-type: none"> Used for HVAC control, running or stopping the inverter, setting or referencing parameters, and monitoring output current, watt-hours, or similar items through LONWORKS communications with peripheral devices.
	CM090	Ethernet option card	<ul style="list-style-type: none"> MODBUS TCP/IP ethernet interface unit.
	SI-T	MECHATROLINK - II option board	<ul style="list-style-type: none"> High speed motion bus. Used for running or stopping the inverter, setting or referencing parameters, and monitoring output frequency, output current, or similar items through MECHATROLINK-II communication with the host controller. Host controller: TrajeXia, MCH or MP series¹

1. Please refer to TrajeXia, MCH or MP series section for host controllers detailed information.t

④ Reference option cards

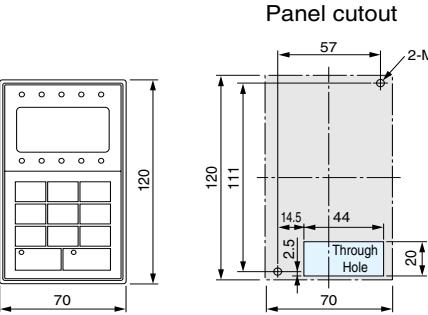
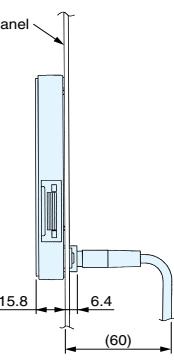
Type	Model	Description	Function
Reference option card	AI-14U / 3G3IV-PAI14U	Analog input card	<ul style="list-style-type: none"> 2 channel high resolution analog input card Channel 1: 0 to 10 V (20 kΩ) Channel 2: 4 to 20 mA (250 Ω) Resolution 14 bit
	AI-14B / 3G3IV-PAI14B		<ul style="list-style-type: none"> 3 Channel high resolution analog input card Signal level: -10 to +10V (20 kΩ) s4 to 20 mA (250 Ω) Resolution: 13 bit + sign
	DI-08 / 3G3IV-PDI08	Digital reference card	<ul style="list-style-type: none"> 8 bit digital speed reference input card
	DI-16H2 / 3G3IV-PDI16H2		<ul style="list-style-type: none"> 16 bit digital speed reference input card

⑤ PLC option cards

Type	Model	Description	Function
PLC option	3G3RV-P10ST8-E	PLC option	<ul style="list-style-type: none"> Full PLC features, wireless installation and seamless access to the inverter parameters and analogue/digital inputs and outputs. Embedded Compubus/S fieldbus Standard OMRON tools can be used for programming
	3G3RV-P10ST8-DRT-E	PLC option with DeviceNet	<ul style="list-style-type: none"> Same features as standard model with DeviceNet support.



⑥ Accessories

Type	Model	Description	Function
Digital operator	JVOP-160-OY	5 lines LCD digital operator 7 language support	
	JVOP-161-OY	7 segment LED digital operator	
Accessories	3G3IV-PCN126 3G3IV-PCN326	Digital operator extension cable 1 meter 3 meters	Extension cable to connect inverter and digital operator.
	3G3IV-PCN329-E	PC configuration cable	Cable to connect the inverter to PC.

⑥ Computer software

Type	Model	Description	Function
Software	CX-drive	Computer software	Configuration and monitoring software tool for drives.
	CX-One	Computer software	Complete OMRON automation software including CX-drive

⑦ Braking unit, braking resistor unit

Inverter			Braking unit		Braking resistor unit ¹								
Voltage	Max. applicable motor output kW	Model CIMR-F7Z_	Model CDBR_	No. of used	Inverter-mounted type (3 %ED, 10 sec max) ²				Separately-installed type (10 %ED, 10 sec. max.) ³				
200 V class	0.4	20P4	Built-in	Model ERF-150WJ_	Resis-tance	No. of used	Braking torque %	Model LKEB_	Specifications of resistor	No. of used	Braking torque %	Connectable min resistance value Ω	
	0.75	20P7		201	200 Ω	1	220	20P7	70 W 200 Ω	1	220	48	
	1.5	21P5		201	200 Ω	1	125	20P7	70 W 200 Ω	1	125	48	
	2.2	22P2		101	100 Ω	1	125	21P5	260 W 100 Ω	1	125	48	
	3.7	23P7		700	70 Ω	1	120	22P2	260 W 70 Ω	1	120	16	
	5.5	25P5		620	62 Ω	1	100	23P7	390 W 40 Ω	1	125	16	
	7.5	27P5						25P5	520 W 30 Ω	1	115	16	
	11	2011						27P5	780 W 20 Ω	1	125	9.6	
	15	2015						2011	2400 W 13.6 Ω	1	125	9.6	
	18.5	2018						2015	3000 W 10 Ω	1	125	9.6	
	22	2022	2022B	1				2015	3000 W 10 Ω	1	125	9.6	
	30	2030	2015B	2				2022	4800 W 6.8 Ω	1	125	6.4	
	37	2037	2015B	2				2015	3000 W 10 Ω	2	125	9.6	
	45	2045	2022B	2				2015	3000 W 10 Ω	2	100	9.6	
	55	2055	2022B	2				2022	4800 W 6.8 Ω	2	120	6.4	
	75	2075	2110B	1				2022	4800 W 6.8 Ω	2	100	6.4	
	90	2090	2110B	1				2022	4800 W 6.8 Ω	3	110	1.6	
	110	2110	2110B	1				2022	4800 W 6.8 Ω	4	120	1.6	
	0.4	40P4	Built in	751	750 Ω	1	230	40P7	70 W 750 Ω	1	230	96	
	0.75	40P7		751	750 Ω	1	130	40P7	70 W 750 Ω	1	130	96	
	1.5	41P5		401	400 Ω	1	125	41P5	260 W 400 Ω	1	125	64	
	2.2	42P2		301	300 Ω	1	115	42P2	260 W 250 Ω	1	135	64	
	3.7	43P7		201	200 Ω	1	110	43P7	390 W 150 Ω	1	135	32	
	4.0	44P0						45P5	520 W 100 Ω	1	135	32	
	5.5	45P5						47P5	780 W 75 Ω	1	130	32	
	7.5	47P5						4011	1040 W 50 Ω	1	135	20	
	11	4011						4015	1560 W 40 Ω	1	125	20	
	15	4015						4018	4800 W 32 Ω	1	125	19.2	
	18.5	4018						4022	4800 W 27.2 Ω	1	125	19.2	
	22	4022	4030B	1				4030	6000 W 20 Ω	1	125	19.2	
	30	4030	4030B	1				4037	9600 W 16 Ω	1	125	12.8	
	37	4037	4045B	1				4045	9600 W 13.6 Ω	1	125	12.8	
	45	4045	4045B	1				4030	6000 W 20 Ω	2	135	19.2	
	55	4055	4030B	2				4045	9600 W 13.6 Ω	2	145	12.8	
	75	4075	4045B	2				4030	6000 W 20 Ω	3	100	3.2	
	90	4090	4220B	1				4030	6000 W 20 Ω	3	100	3.2	
	110	4110	4220B	1				4045	9600 W 13.6 Ω	4	140	3.2	
	132	4132	4220B	1				4045	9600 W 13.6 Ω	4	140	3.2	
	160	4160	4220B	1				4045	9600 W 13.6 Ω	4	120	3.2	
	185	4185	4220B	1				4045	9600 W 13.6 Ω	4	110	3.2	
	220	4220	4220B	1				4037	9600 W 16 Ω	5	110	3.2	
	300	4300	4220B	2				4045	9600 W 13.6 Ω	6	110	3.2	

- When connecting a mounting type resistor or braking resistor unit, set system constant L3-04 to 0 (stall prevention disabled during deceleration). If operating without changing the constant, motor does not stop at set deceleration time.
- When connecting mounting type braking resistor, set system constant L8-01 to 1 (braking resistor protection enabled).
- Load factor during deceleration to stop a load with constant torque. With constant output or continuous regenerative braking, the load factor is smaller than the specified value.
- Resistance value per one braking unit. Select a resistance value that is larger than connectable minimum resistance value to obtain enough braking torque.
- For an application with large regenerative power such as hoisting, the braking torque or other items may exceed the capacity of a braking unit with a braking resistor in a standard combination (an result in capacity overload). Contact your OMRON representatives when the braking torque or any other item exceeds the values in the table.